

eExam Question Bank

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<input type="checkbox"/>	Question Type	Question	A	B	C	D	Ans
<input type="checkbox"/>	FBQ	If any matrix A is transformed into another matrix B by a series of elementary row operations, then A and B are <input type="text"/> matrices.	equivalent				
<input type="checkbox"/>	FBQ	$1 + \frac{x}{1!} + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$ is the <input type="text"/> series for $\exp x$	Maclaurin's	maclaurin			
<input type="checkbox"/>	FBQ	If the Lagrange's interpolation polynomial of $f(x)$ is given as $x^3 - x^2 + 3x + 8,$ then $f(2) = 1$ is <input type="text"/>	8	eight			
<input type="checkbox"/>	FBQ	Given that $f(3) = 168$, $f(7) = 120$, $f(3) = 72$ and $f(10) = 63$, the approximate value for $f(6)$ is <input type="text"/>	147				
<input type="checkbox"/>	FBQ	If $AB = BA = I$, then A is the <input type="text"/> of B	inverse				
<input type="checkbox"/>	FBQ	<input type="text"/> is the determinant of the system of equations: $4x_1 + x_2 + x_3 = 4$ $x_1 + 4x_2 - 2x_3 = 4$ $-x_1 + 2x_2 - 4x_3 = 2$	36				
<input type="checkbox"/>	FBQ	Given that the Lagrange's interpolating polynomial $P(x)$ is given by $P(x) = L_0(x)f_0 + L_1(x)f_1 + L_2(x)f_2 + L_3(x)f_3$ Hence, if $f(1) = -3$, $f(3) = 9$, $f(4) = 30$ and $f(6) = 132$, therefore Lagrange fundamental polynomial $L_0(x)$ will be <input type="text"/>	7	seven			
<input type="checkbox"/>	FBQ	A matrix having the same number of rows and columns is called <input type="text"/> matrix	square	Square			
<input type="checkbox"/>	FBQ	A matrix in which all the non-diagonal elements vanish is known as <input type="text"/> matrix.	diagonal				

<input type="checkbox"/>							
<input type="checkbox"/>	FBQ	A system of linear equations is said to be <input type="text"/> if it has at least one solution.	homogeneous				
<input type="checkbox"/>	FBQ	The transpose of the cofactor matrix of a square matrix A is called the <input type="text"/> of A	adjoint	Adjoint			
<input type="checkbox"/>	FBQ	A matrix A = (aij) in which aij = 0 (i, j = 1, 2 n) is called <input type="text"/>	NULL	Null			
<input type="checkbox"/>	FBQ	Determinant is a number associated with <input type="text"/> matrices.	square	Square			
<input type="checkbox"/>	FBQ	A matrix A is <input type="text"/> if and only if it has a zero eigenvalue	singular				
<input type="checkbox"/>	FBQ	The process of determining the value of f(x) for a value of x lying outside the interval [a, b] is called <input type="text"/>	extrapolation				
<input type="checkbox"/>	MCQ	Iterative methods of the solutions of systems of equations are	finite	infinite	sequential	non-sequential	B
<input type="checkbox"/>	MCQ	One of these is not a method of solving system of linear equations	Inverse method	elimination method	Determinant method	Solution method	D
<input type="checkbox"/>	MCQ	The following statements are true except	The backward-difference form is suitable for approximating the value of the function at x that lies towards the end of the table.	Stirling's method is used whenever interpolation is required of x near the middle of the table of values.	\[For\; the\; central\; difference\; formulas\; the\; \;origin\; x_0\;,\; should\; not\; be\; chosen\; near\; the\; point\; being\; approximated.\]	The Stirling's interpolation is used for calculation when x lies between $[x_0 - \frac{1}{4}h, x_0 + \frac{1}{4}h]$	C
<input type="checkbox"/>	MCQ	The following statements are true except	The divided difference is independent of the order of its arguments.	The identity matrix I is a diagonal matrix in which all the diagonal elements are equal to one	A square matrix is lower triangular if all the elements above the main diagonal vanish .	The divided difference is dependent of the order of its arguments.	D
<input type="checkbox"/>	MCQ	One of the following is not true	Two matrices A and B can be multiplied only if the number of columns of A equals the number of rows of B.	Addition of matrices is defined only for matrices of same order.	Two matrices A and B can be multiplied only if the number of columns of B equals the number of rows of A.	A square matrix is lower triangular if all the elements above the main diagonal vanish.	A
<input type="checkbox"/>	MCQ	The backward differences of order three $\nabla^3 f_k$ is denoted by	$\nabla^3 f_k = f_k - 3f_{(k-2)} - 3f_{(k-2)} - f_{(k-3)}$	$\nabla^3 f_k = f_k - 3f_{(k-2)} - 3f_{(k-2)} - f_{(k-3)}$	$\nabla^3 f_k = f_k - 3f_{(k-2)} - 3f_{(k-2)} - f_k$	$\nabla^3 f_k = f_k - 3f_{(k-2)} - 3f_{(k-2)} - f_k$	B
<input type="checkbox"/>	MCQ	The inverse of the matrix $\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 0 \\ 6 & 0 & 0 \end{bmatrix}$ is;	$\begin{bmatrix} 1 & \frac{-1}{3} & \frac{1}{3} \\ \frac{-1}{2} & \frac{1}{2} & \frac{1}{2} \\ \frac{-5}{24} & \frac{1}{24} & \frac{1}{6} \end{bmatrix}$	$\begin{bmatrix} 1 & \frac{-1}{2} & \frac{1}{12} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{4} \\ \frac{5}{24} & \frac{1}{24} & \frac{1}{6} \end{bmatrix}$	$\begin{bmatrix} 1 & \frac{-1}{2} & \frac{1}{12} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{4} \\ \frac{-5}{24} & \frac{1}{24} & \frac{1}{6} \end{bmatrix}$	$\begin{bmatrix} 1 & \frac{-1}{2} & \frac{1}{3} \\ \frac{1}{2} & \frac{1}{2} & \frac{1}{4} \\ \frac{-5}{24} & \frac{1}{24} & \frac{1}{6} \end{bmatrix}$	C
<input type="checkbox"/>	MCQ	If the inverse of matrix B exists, then it is	universal	unique	united	unlimited	B

<input type="checkbox"/>	MCQ	Stirling's formula for interpolation is given by	$\frac{P_n(x) - f(x_0)}{(x-x_0)^2} = \frac{f'(x_0)}{2!} + \frac{f''(x_0)}{3!}(x-x_0) + \dots$	$\frac{P_n(x) - f(x_0)}{(x-x_0)^2} = \frac{f'(x_0)}{2!} + \frac{f''(x_0)}{3!}(x-x_0) + \dots$	$\frac{P_n(x) - f(x_0)}{(x-x_0)^2} = \frac{f'(x_0)}{2!} + \frac{f''(x_0)}{3!}(x-x_0) + \dots$	$\frac{P_n(x) - f(x_0)}{(x-x_0)^2} = \frac{f'(x_0)}{2!} + \frac{f''(x_0)}{3!}(x-x_0) + \dots$	D
<input type="checkbox"/>	MCQ	One of the following is true	$\Delta^3 f_4 = f_4 - f_3$	$\Delta^3 f_4 = f^4 - f^3$	$\Delta^3 f_4 = f_5 - f_4$	$\Delta^3 f_4 = f_3 + f_4$	A
<input type="checkbox"/>	MCQ	The inverse of a matrix A is given by	$A^{-1} = \frac{1}{\det(A)} \text{adj}(A)$	$A^{-1} = \frac{1}{\det(A)}$	$A = \frac{1}{\det(A)} \text{adj}(A)$	$A = \det(A) \text{adj}(A)$	A
<input type="checkbox"/>	MCQ Theorem states that 'If f is a continuous function defined on [a, b] and differentiable on]a, b[; and If f(a) = f(b), then there exists a number $x_0 \in]a, b[$; such that $f'(x_0) = 0$	Pythagoras	Chebyshev	Rolle's	Lagrange's Mean Value	C
<input type="checkbox"/>	MCQ	The Lagrange's interpolating polynomial P(x) is given by	$P(x) = L_0(x)f_0 + L_1(x)f_1 + L_2(x)f_2 + L_3(x)f_3$	$P(x) = L_0(x)f_3 + L_1(x)f_2 + L_2(x)f_1 + L_3(x)f_0$	$P(x) = L_0(x)f_0 + L_1(x)f_1 + L_2(x)f_2 + L_3(x)f_3$	$P(x) = L_0(x)f_0 + L_1(x)f_2 + L_2(x)f_2 + L_3(x)f_3$	C
<input type="checkbox"/>	MCQ	Solve the system of equations: $a + b + c = 1$ $4a + 3b - c = 6$ $3a + 5b + 3c = 4$	$a = 1/2 ; b = -1 ; c = -1/2$	$a = 1/2 ; b = 1 ; c = -2$	$a = 1 ; b = 1/2 ; c = -1/2$	$a = 1/2 ; b = 1 ; c = -1/2$	C
<input type="checkbox"/>	MCQ	The interpolating polynomial of degree $\leq n$; with the nodes x_0, x_1, \dots, x_n can be written as	$P_n(x) = \sum_{k=0}^n \frac{f(x_k)}{w(x_k)} \prod_{j \neq k} \frac{(x-x_j)}{(x_k-x_j)}$	$P_n(x) = \sum_{k=0}^n \frac{f(x_k)}{w(x_k)}$	$P_n(x) = w(x) \sum_{k=0}^n \frac{f(x_k)}{(x-x_k)(x_k-x_j)}$	none of the above	A
<input type="checkbox"/>	MCQ	Find the inverse of the matrix $\begin{pmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{pmatrix}$	$\begin{pmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{pmatrix}$	$\begin{pmatrix} 1 & -1/2 & 1/4 \\ 0 & 1 & 5/4 \\ 0 & 0 & 6 \end{pmatrix}$	$\begin{pmatrix} 1 & 1/2 & 1/4 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{pmatrix}$	$\begin{pmatrix} 1 & 1/2 & 1/4 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{pmatrix}$	B
<input type="checkbox"/>	MCQ	$\Delta^2 f_k = \dots$	$f_{k+1} - f_k$	$\Delta f_{k+1} - \Delta f_k$	$f_{k+2} - 2f_{k+1} + f_k$	All the options	D
<input type="checkbox"/>	MCQ	Let x_0, x_1, \dots, x_n be $(n+1)$ distinct points on the real line and $f(x)$ be a real-valued function defined on some interval $I = [a, b]$ containing these points, then	there exists more than one polynomial of degree n	there exists exactly one polynomial of degree n	there exists two polynomials of degrees n and $n+1$	no polynomial of degree n exists	B
<input type="checkbox"/>	MCQ	A system of linear equations is said to be if not all its right hand side is zero	consistent	inconsistent	homogeneous	non-homogeneous	D
<input type="checkbox"/>	MCQ	The eigenvalues of a diagonal matrix are	0 & 1	the diagonal elements themselves	all zeroes	all unity	B

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